LCM Channels Naming Conventions

Each robot type we are going to agree ahead of time what each LCM channel corresponds to. The convention will be [channel]|[id number].

Each User ID must be greater than 2. When a roboto’s current userID is -1, it is in autonomous, if it is -2, it is stopped. If it is [Some user’s userID] than the robot is being teleoperated. . If it is -1 \* [Some user’s userID] than the robot is in autonomous but is being supervised by the user.